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STATEMENT BY APPLICANT****(Not for submission under 37 CFR 1.99)**

Application Number	10634874
Filing Date	2003-08-06
First Named Inventor	Babak Habibi
Art Unit	3664
Examiner Name	Marc McDieunel
Attorney Docket Number	170154.401C1

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	4	6115480		2000-09-05	Washizawa	
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1	20030007159	A1	2003-01-09	Franke et al.	
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	3	Denzler J., et al., "Learning, Tracking and Recognition of 3D Objects," Proceedings of the IEEE/RSJ/IGI, International Conference on Intelligent Robots and Systems (IROS) 1:89-96, 1994.	<input type="checkbox"/>

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4	Ji, Q., et al., "An Integrated Linear Technique for Pose Estimation from different Geometric Features," International Journal of Pattern Recognition and Artificial Intelligence, 13(5):705-733, August 1999.	<input type="checkbox"/>
5	Jia, Y-B., et al., "Sensing Polygon Poses by Inscription," Proc. of 1994 IEEE International Conference on Robotics and Automation, pp. 1642-1649, May 1994.	<input type="checkbox"/>
6	Kim, W.S., "Computer vision assisted virtual reality calibration," URL= http://www.robotics.jpl.nasa.gov/publications/Won_Kim/ra98_vrc.pdf , pp. 1-14, 1999.	<input type="checkbox"/>
7	Kovacic, S., et al., "Planning Sequences of Views for 3-D Object Recognition and Pose Determination," Pattern Recognition 31(10):1407-1417, 1998.	<input type="checkbox"/>
8	Sanchez, A., et al., "Robot-arm Pick and Place Behavior Programming System Using Visual Perception," in Proceedings of the 15th International Conference on Pattern Recognition 4:507-510, September 2000.	<input type="checkbox"/>
9	Tsai, R. et al., "An Efficient and Accurate Camera Calibration Technique for 3D Machine Vision," Proceedings of IEEE, Conference on Computer Vision and Pattern Recognition, pp. 364-374, 1986.	<input type="checkbox"/>
10	Tsai, R., "A Versatile Camera Calibration Technique for High-Accuracy 3D Machine Vision Metrology Using Off-the-Shelf TV Cameras and Lenses," IEEE Journal of Robotics and Automation, RA-3(4):323-344, August 1987.	<input type="checkbox"/>

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